

Integrating PROB into the TLA Toolbox

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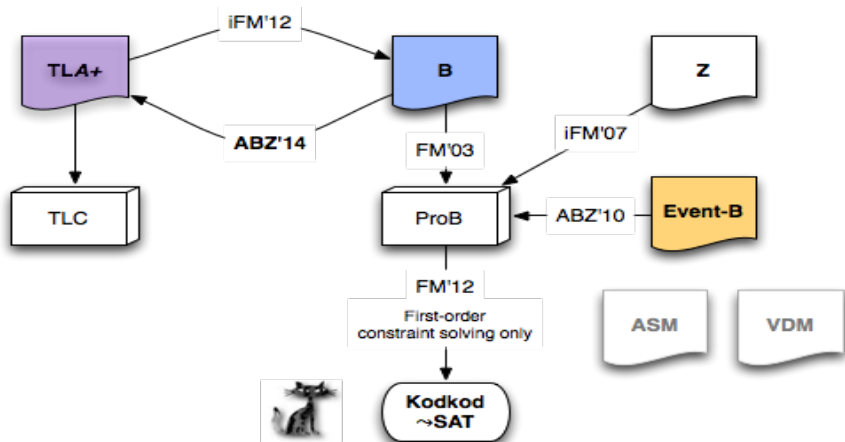
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Demo

What is PROB?

- ▶ Model checker, animator and constraint solver
- ▶ Other features
 - ▶ Visualization (Model, Statespace, Formulas, Value over time)
 - ▶ LTL model checker
 - ▶ Profiler (Event coverage, value coverage, ...)
 - ▶ Disprover
- ▶ PROB kernel is written in prolog
- ▶ Originally designed to validate Classical B specifications
- ▶ Other supported formal languages:
 - ▶ EventB, Z, ...
 - ▶ TLA⁺

Supported Formal Languages



TLA2B translator

- ▶ Full automatic translation tool
- ▶ Build upon SANY
- ▶ Type inference algorithm
- ▶ Uses a TLC run configuration
- ▶ New version
 - ▶ Creating the extended B abstract syntax tree
 - ▶ No renaming phase
 - ▶ No need to extend the B language

Supported subset of TLA⁺

- ▶ Data values
 - ▶ Integers, boolean values, strings, sets, functions, records
 - ▶ TLC's model values
- ▶ Operators
 - ▶ All non temporal built-in operators
 - ▶ Standard modules (Naturals, Integers, Sequences, ...)
 - ▶ User-defined operators
- ▶ Recursive Functions
- ▶ Extends & Instance

Restrictions

- ▶ Restriction caused by the B type system
 - ▶ Only values of the same type can be mixed in a set
 - ▶ Model values can not be compared to other values
 - ▶ Variables and constants must have a fixed type
- ▶ Temporal operators are not supported
- ▶ Recursive definitions are not supported yet

Toolbox Integration

- ▶ Existing plugin for the Eclipse based RODIN platform
- ▶ Almost independent from RODIN
- ▶ Reuse of all UI elements
- ▶ Toolbox plugin
 - ▶ UI bindings for the Toolbox
 - ▶ Code for loading TLA⁺ models
 - ▶ Small changes to the product and target definitions of the toolbox

RODIN Integration

The screenshot displays the Rodin Platform interface for a lift system model. The main window is titled "ProB - Lift/MLift.bum - Rodin Platform".

Events View: Lists various events such as `move_up()`, `move_down()`, `reverse_lift_down()`, `reverse_lift_up()`, `open_door()`, `close_door()`, `push_inside_button(0)`, `push_inside_button(1)`, `push_call_button(-1)`, `push_call_button(0)`, and `push_call_button(1)`.

MLift Machine Model:

```
MACHINE
  SEES
    * Clift
  VARIABLES
    * cur_floor
    * inside_buttons
    * door_open
    * call_buttons
    * direction_up
  INVARIANTS
    * inv1: cur_floor ∈ {groundf, topf} not theorem
    * inv2: inside_buttons c {groundf, topf} not theo
    * inv3: door_open ∈ BOOL not theorem
    * inv4: call_buttons g {groundf, topf} not theorem
    * inv5: direction_up ∈ BOOL not theorem
  EVENTS
    * INITIALISATION: not extended ordinary
    THEN
      * act1: cur_floor = groundf
      * act2: inside_buttons = 0
      * act3: door_open = FALSE
```

ProB2 View: Shows the state space graph with nodes representing states and transitions representing events. The initial state is highlighted in green. States include variables like `cur_floor`, `direction_up`, `door_open`, `inside_buttons`, and `call_buttons`.

Diagram: A vertical diagram showing three floors: Floor 1, Floor 0, and Floor -1. A grey rectangle represents the lift car, currently positioned on Floor 0.

Current Trace: Shows the execution of `move_down()` with the following code:

```
move_down()
move_down()
reverse_lift_down()
move_up()
move_up()
$initialise_machine({}, -1, TRUE, FALSE, {})
$setup_constants(-1.1)
-- root --
```

MLift Properties:

Variables	Value
call_buttons	0
cur_floor	-1
direction_up	FALSE
door_open	FALSE
inside_buttons	0

Invariants:

- cur_floor ∈ {groundf, topf}
- inside_buttons c {groundf, topf}
- door_open ∈ BOOL
- call_buttons g {groundf, topf}
- direction_up ∈ BOOL

Sets:

- cur_floor = -1

Constants:

- None listed

Axioms:

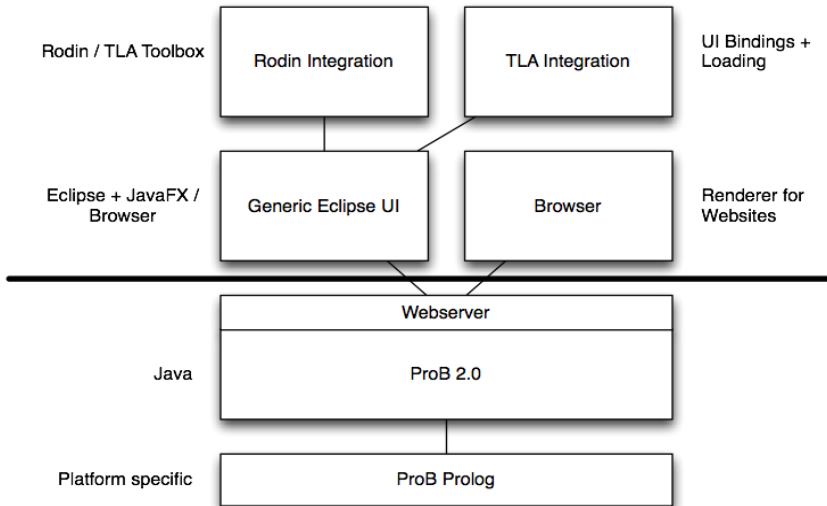
- None listed

Current & Future Work

- ▶ Extending the translation
 - ▶ Recursive operators
 - ▶ Temporal formulas
- ▶ Interaction of PROB and TLC
 - ▶ Using PROB to setup the constants
 - ▶ Replaying traces produced by TLC in the animator
- ▶ Toolbox plugin
 - ▶ TLA⁺ syntax in the evaluation console
 - ▶ Back-translation of B expression
 - ▶ Perspective & Views
 - ▶ Release of a stand-alone version

Questions?

PROB Architecture



B-Method & TLA⁺

	TLA ⁺	B-Method
Invented by	Leslie Lamport	J.R. Abrial
State-based	✓	✓
Set theory	✓	✓
Predicate logic	✓	✓
Arithmetic	✓	✓
Temporal formulas	✓	X
Type system	X	✓
State transitions	Before-after predicates	Generalised substitutions
Model checker	TLC	PROB
Prove support	TLAPS	AtelierB

PROB & TLC

	PROB	TLC
Animation	✓	
Model Checking	✓ (Symmetry reduction, Partial order Reduction)	✓ (Symmetry reduction)
Disk-Based		✓
Parallelisation	✓	✓
Temporal Properties	✓	✓
Constraint Solving	✓ (Inductive Inv. check, Disprover, ...)	
Graphical Visualization	✓ (State, Formulas, Traces, Statespace)	
Coverage	✓ (Profiling, Event coverage, Value Coverage, ...)	✓ (Action coverage)

Translation of an example

```
MODULE HourClock  
EXTENDS Naturals  
CONSTANTS start  
VARIABLES hr  
ASSUME start  $\in$  0 .. 12
```

```
Inv  $\triangleq$  hr  $\in$  0 .. 12  
Init  $\triangleq$  hr = start  
Inc  $\triangleq$  hr < 12  $\wedge$  hr' = hr + 1  
Reset  $\triangleq$  hr = 12  $\wedge$  hr' = 1  
Next  $\triangleq$  Inc  $\vee$  Reset
```

```
MACHINE HourClock  
CONSTANTS start  
VARIABLES hr  
PROPERTIES start  $\in$  0 .. 12  
INVARIANT hr  $\in$  0 .. 12  
INITIALISATION hr : (hr = start)  
OPERATIONS  
  Inc = ANY hr_n  
    WHERE hr < 12  $\wedge$  hr_n = hr + 1  
    THEN hr := hr_n END  
  
  Reset = ANY hr_n  
    WHERE hr = 12  $\wedge$  hr_n = 1  
    THEN hr := hr_n END  
END
```